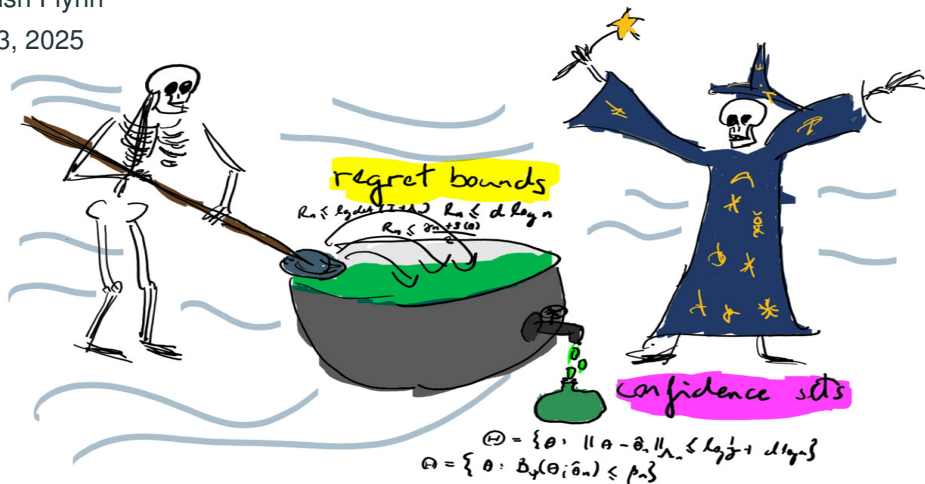


Confidence Sequences for Generalised Linear Models via Regret Analysis

Hamish Flynn

July 3, 2025



Warmest Thanks



Eugenio Clerico



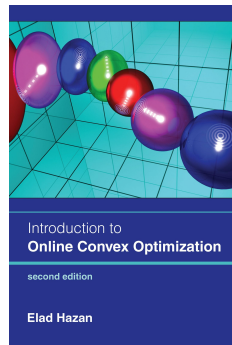
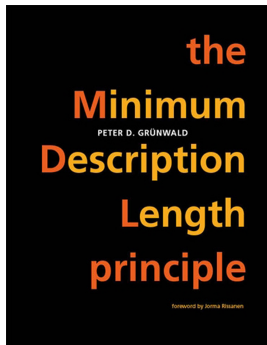
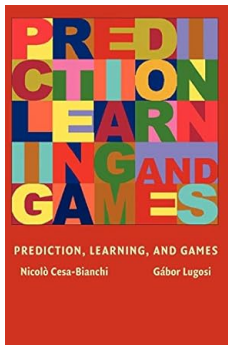
Wojciech Kotłowski



Gergely Neu

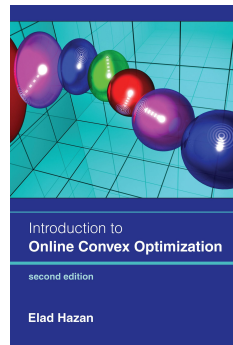
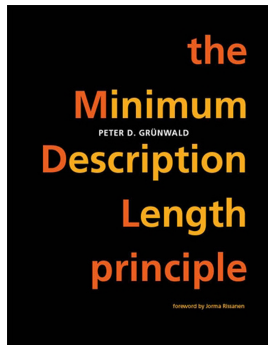
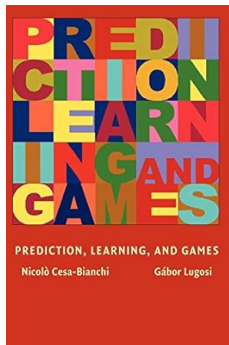
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Assume we know a bit about online learning (or universal coding).



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We want to construct confidence sequences for GLMs without doing any actual work.

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Generalised Linear Model:

- Covariates $X_1, \dots, X_n \in \mathbb{R}^d$
- Responses $Y_1, \dots, Y_n \in \mathbb{R}$
- Likelihood $p(Y_t|X_t, \theta^*) = \exp(\langle \theta^*, x \rangle y - \psi(\langle \theta^*, x \rangle)) h(y)$

The log-partition function $\psi : \mathbb{R} \rightarrow \mathbb{R}$ is convex.

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Oblivious Design: X_t does not depend on Y_1, \dots, Y_{t-1} .

Objective and Claim

Adaptive Design: For $\delta \in (0, 1]$, a δ -*confidence sequence* for θ^* is a sequence of sets $\Theta_1, \Theta_2, \dots$, such that

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$$\Theta_n = \left\{ \theta : \sum_{t=1}^n \ell_t(\theta) - \inf_{\theta' \in \mathbb{R}^d} \sum_{t=1}^n \ell_t(\theta') \leq \beta_n \right\}$$

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Online-to-confidence-set conversion: Use the output and/or regret bound of an online learning algorithm to determine β_n .

Claim: We can recover all confidence sequences for GLMs via OTCS (at least all confidence sequences with non-asymptotic coverage guarantees).

Online-To-Confidence-Set Conversion

(for adaptive design)

Sequential Probability Assignment

Protocol: For $t = 1, 2, \dots, n$:

1. Environment reveals X_t to the learner
2. Learner picks $Q_t \in \Delta_\Theta$ with density q_t
3. Environment reveals Y_t to the learner,
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$$\text{regret}_{q^n}(\bar{\theta}) = \sum_{t=1}^n (\mathcal{L}_t(q_t) - \ell_t(\bar{\theta})) .$$

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Note: This can be made more general by playing distributions on \mathcal{Y} (see our paper).

Online-To-Confidence Set Conversion (Adaptive Design)

For any sequence of comparators $\bar{\theta}_1, \bar{\theta}_2, \dots$ and any \mathbb{F} -predictable q^n , the sets $\Theta_1, \Theta_2, \dots$ form a δ -CS, where

$$\Theta_n = \left\{ \theta \in \mathbb{R}^d : \sum_{t=1}^n (\ell_t(\theta) - \ell_t(\bar{\theta}_n)) \leq \text{regret}_{q^n}(\bar{\theta}_n) + \log \frac{1}{\delta} \right\}.$$

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Next, we notice that the second term is the logarithm of a non-negative \mathbb{F} -martingale.

$$\exp \left(\sum_{t=1}^n (\ell_t(\theta^*) - \mathcal{L}_t(q_t)) \right) = \prod_{t=1}^n \int \frac{p(Y_t|X_t, \theta)}{p(Y_t|X_t, \theta^*)} q_t(\theta) \, d\theta.$$

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Therefore,

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(for oblivious design)

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As long as the design is oblivious, the second term is the logarithm of a non-negative $\tilde{\mathbb{F}}$ -martingale. Therefore,

$$\mathbb{P} \left(\sum_{t=1}^n (\ell_t(\theta^*) - \ell_t(\bar{\theta}_n)) \geq \text{regret}_{q^n}(\bar{\theta}_n) + \log \frac{1}{\delta} \right) \leq \delta.$$

Online-To-Confidence-Set Conversions for Smooth GLMs

Bregman Divergence and Bregman Information Gain

For a convex differentiable function $f : \mathbb{R}^d \rightarrow \mathbb{R}$, the *Bregman divergence* is

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For a convex differentiable function $\rho : \mathbb{R}^d \rightarrow \mathbb{R}$, let $Z_n^\rho(\theta) = \sum_{t=1}^n \ell_t(\theta) + \rho(\theta)$ and $\hat{\theta}_n = \operatorname{argmin}_{\theta \in \mathbb{R}^d} Z_n^\rho(\theta)$.

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The *Bregman information gain* is

$$\gamma_n^\rho = -\log \left(\frac{\int \exp(-\mathcal{B}_{Z_n^\rho}(\theta, \hat{\theta}_n)) d\theta}{\int \exp(-\rho(\theta)) d\theta} \right).$$

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If ψ is M -smooth ($|\psi''(z)| \leq M$) and $\rho = \frac{1}{2\gamma^2} \|\theta\|_2^2$, then

$$\gamma_n^\rho \leq \frac{1}{2} \log \det(M\gamma^2 \Lambda_n + \operatorname{Id}) \leq \frac{d}{2} \log(1 + \frac{\gamma^2 M L^2 n}{d}),$$

where $\Lambda_n = \sum_{t=1}^n X_t X_t^\top$ and $L = \max_{t \in [n]} \|X_t\|_2$.

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Claim: For any choice of ρ ,

$$\text{regret}_{q^n}(\bar{\theta}_n) \leq \gamma_n^\rho + \rho(\bar{\theta}_n) .$$

OTCS for Smooth GLMs (Adaptive Design)

Suppose that ψ is M -smooth, and fix $\gamma > 0$. Set $\rho = \frac{1}{2\gamma^2} \|\theta\|_2^2$ and let $\hat{\theta}_n = \operatorname{argmin}_{\theta \in \mathbb{R}^d} \{\sum_{t=1}^n \ell_t(\theta) + \rho(\theta)\}$.

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This matches the one you would get from self-normalised concentration (with slightly better constants).

OTCS for Oblivious Design

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$$\mathcal{B}_\Psi(\theta^*, \hat{\theta}_{n,b}) \leq \sum_{t=1}^n \ell_t(\theta) - \sum_{t=1}^n \ell_t(\hat{\theta}_{n,b}), \quad \text{and} \quad \frac{1}{2\gamma^2} \|\hat{\theta}_{n,b} - \theta^*\|_{\Lambda_n}^2 \leq \frac{1}{m\gamma^2} \mathcal{B}_\Psi(\theta^*, \hat{\theta}_{n,b}).$$

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$$\Theta_n = \left\{ \theta : \|\theta - \hat{\theta}_{b,n}\|_{\Lambda_n}^2 \leq 2d \log(3) + 4 \log \frac{1}{\delta} \right\}.$$

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The end. Thank you!